

CONTENTS

CHAPTER 1 - GENERAL INFORMATION

1-1	SYSTEM DESCRIPTION	1-1
1-2	ROBOT ARM	1-2
1-3	RSC-P8/PID8 ROBOT SYSTEM CONTROLLER	1-4
1-4	TEACH PENDANT	1-8

CHAPTER 2 - SPECIFICATIONS

2-1	ROBOT ARM	2-1
2-2	ROBOT SYSTEM CONTROLLER	2-5
2-3	TEACH PENDANT	2-6

CHAPTER 3 - PREPARATION FOR USE

3-1	UNPACKING AND INSPECTION	3-1
3-2	ROBOT BASE INSTALLATION	3-2
3-3	GRIPPER INSTALLATION	3-3
3-4	RSC-M1A ROBOT SYSTEM CONTROLLER INSTALLATION	3-4
3-5	CABLING	3-7
3-6	SERIAL DEVICE CONNECTIONS	3-8
3-7	DIGITAL I/O INSTALLATION (OPTIONAL)	3-10
3-8	ANALOG INPUT INSTALLATION (OPTIONAL)	3-12

CHAPTER 4 - PRECAUTIONS FOR USE

4-1	SAFETY	4-1
4-2	HANDLING OF ROBOT	4-1
4-3	POWER FAIL	4-1

CHAPTER 5 - START-UP OPERATIONS

5-1	POWER UP SEQUENCE	5-1
5-2	HOMING SEQUENCE	5-2

CHAPTER 6 - MECHANICAL DESCRIPTION

6-1	ROBOT ARM CONSTRUCTION	6-1
6-2	DRIVE MOTORS	6-2
6-3	DRIVES AND TRANSMISSIONS	6-3

CHAPTER 7 - ELECTRONIC DESCRIPTION

7-1	INTRODUCTION	7-1
7-2	MOTHERBOARD	7-3
7-3	DC AMPLIFIER MODULE	7-7
7-4	SERVO AXIS CARDS	7-9
7-5	PID-TYPE SERVO AXIS CARDS	7-11
7-6	FRONT PANEL LOGIC BOARD	7-16
7-7	I/O TERMINATION BOARD	7-19
7-8	COMPUTER POWER SUPPLY	7-20
7-9	ARM POWER SUPPLY	7-20
7-10	ARM POWER FILTER BOARD	7-20
7-11	ENCODER CONNECTOR BOARD	7-21
7-12	AMP EXPANSION BOARD	7-22

CONTENTS (Continued)

CHAPTER 8 - SOFTWARE DESCRIPTION

8-0	INTRODUCTION	8-1
8-1	MEMORY MANAGEMENT	8-1
8-2	COMPUTATIONAL ACCURACY	8-1
8-3	PATH CONTROL - CLOSED LOOP CONTROL	8-2
8-4	PATH CONTROL - COMMAND GENERATION	8-3
8-5	INPUT/OUTPUT SCANNING	8-6
8-6	MEMORY ALLOCATION	8-6

CHAPTER 9 - HOMING BRACKET INSTALLATION

9-1	INTRODUCTION	9-1
9-2	HOMING BRACKET INSTALLATION	9-1
9-3	ROBOT RE-CALIBRATION	9-2
9-4	AUTO START PROGRAM	9-4

APPENDIX A - RAPL-II MONITOR FUNCTIONS

APPENDIX B - ADVANCED COMMUNICATION INTERFACE (ACI)

APPENDIX C - MECHANICAL MAINTENANCE

APPENDIX D - MECHANICAL DRAWINGS

APPENDIX E - OPTICAL ENCODER SPECIFICATIONS

APPENDIX F - CONTROL SYSTEM DETAILED TECHNICAL DESCRIPTION

APPENDIX G - RAPL-II CONTROL PARAMETER LIST

APPENDIX H - 'C' PROGRAMMING HINTS

APPENDIX I - RAPL-II BIOS INTERFACE

APPENDIX J - USE OF EXTRA AXES

FIGURES

1-1	A150 Series Small Industrial Robot System	1-1
1-2	A100/200 Series Robot Arm	1-2
1-3	Motor Connector	1-3
1-4	Robot System Controller - Front and Rear Views	1-4
1-5	A100/200 Series System Controller (Front Panel)	1-5
1-6	A100/200 Series System Controller (Back Panel)	1-6
1-7	Teach Pendant	1-8
2-1	Workspace Plan	2-3
2-2	Workspace Elevation	2-4

FIGURES (Continued)

3-1	Robot Base Dimensions	3-2
3-2	Robot Gripper Mounting Dimensions	3-3
3-4	Controller Dimensions	3-6
3-5	Video Terminal Cable pin-out	3-8
3-6	Printer Cable pin-out	3-9
3-7	Pin orientation for each digital I/O connector	3-10
3-8	Digital I/O Pinout Description	3-11
3-9	Analog Input pin description with optional COMBO expansion card.	3-12
3-10	Analog input connector pin location diagram	3-12
5-1	Homing Marks - Setup Position	5-3
6-1	Robot Joints	6-1
6-3	Optical Encoder Schematic	6-2
6-4	Harmonic Drive	6-4
7-1	A100/200 Controller (Lid removed and front panel dropped)	7-1
7-2	Motherboard P.C.B.	7-3
7-3	D.C. Amplifier Module	7-7
7-4	Servo Axis Card	7-9
7-6	Front Panel Logic Board	7-16
7-7	I/O Termination Board - Viewed from inside controller box.	7-19
7-8	The Encoder Connector Board.	7-21
7-9	The Amp Expansion Board	7-22
9-1	Correct Robot Location Relative to Bracket	9-2

TABLES

1-1	E-STOP/AUX. INPUT Connection Pin-out	1-7
2-1	Robot Arm Specifications	2-1
2-2	RSC-P8/PID8 Robot System Controller Specifications	2-5
2-3	Teach Pendant Specifications	2-6
3-1	A100/200 Series - System Components	3-1
6-1	Robot Joints: Ranges of Motion	6-2
7-1	A100/200 Series Controller Description	7-2
7-2	Mother-Board Layout	7-4
7-4	Servo Axis Card Descriptio	7-10
8-1	Memory Map	8-10